

# Stability of Control System of Intracellular Iron Homeostasis: A Mathematical Proof

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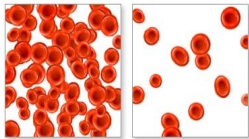
# Blood Donor Eligibility

- Frequently asked questions
  - ▶ Age
  - ▶ Weight
  - ▶ Medical History
- Hemoglobin Levels
  - ▶ Red blood cells



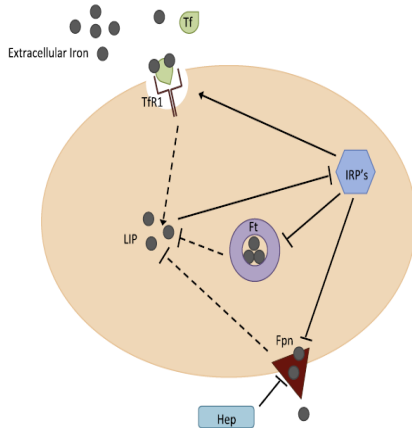
# Background

- Importance of iron in the blood cells
  - ▶ Essential for cellular metabolism
  - ▶ The levels are tightly constrained



- “The core control system of intracellular iron homeostasis: A Mathematical model” [1]
  - ▶ Principal paper that presents the mathematical model of the control system

# Chifman *et al.* Model



- The solid lines indicate positive or negative regulation.
- The dotted line are reactions that consume or produce the indicated species.

# The ODE's that define the mathematical model

- The  $x_i$  with  $i \in \{1, \dots, 5\}$  is an activating/inhibiting state variable.

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5},$$

$$\dot{x}_2 = \alpha_2 \frac{x_5}{k_{52} + x_5} - \gamma_2 x_2,$$

$$\dot{x}_3 = \alpha_3 \frac{k_{53}}{k_{53} + x_5} - (\gamma_3 + \gamma_h Hep) x_3,$$

$$\dot{x}_4 = \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5} - \gamma_4 x_4,$$

$$\dot{x}_5 = \alpha_5 \frac{k_{15}}{k_{15} + x_1} - \gamma_5 x_5.$$

# The ODE's that define the mathematical model

- The  $k_{nj}$  is the activation threshold for  $n \in \{1, 5\}$  and  $j \in \{2, 3, 4, 5\}$ .

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5},$$

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# The ODE's that define the mathematical model

- The  $\alpha_\ell$  is the maximum production rate of the regulated protein for  $\ell \in \{1, \dots, 6\}$

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# The ODE's that define the mathematical model

- Each protein undergoes self-degradation, thus each protein has a decay rate  $\gamma_j$ .

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5},$$

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# The ODE's that define the mathematical model

- $Hep$  and  $Fe_{ex}$  are control parameters, so they are considered constants fixed between 0 and 1.

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5},$$

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## Steady state of the system

- This system has a unique solution which is:

$$P(x_1) = ax_1^3 + bx_1^2 \pm cx_1 - d = 0$$

where  $a$ ,  $b$ ,  $c$  and  $d > 0$ , where

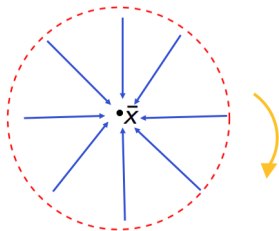
$$a = \alpha_3 \alpha_6 \gamma_2 (\gamma_5^2) k_{52} k_{53},$$

$$b = \alpha_3 \alpha_6 \gamma_2 \gamma_5 k_{15} k_{53} (\alpha_5 + 2\gamma_5 k_{52}),$$

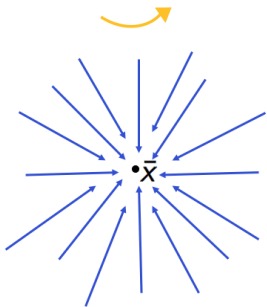
$$c = \gamma_5 k_{15} (-\alpha_1 \alpha_2 \alpha_5 Fe_{\text{ex}} (\gamma_3 + \hat{\gamma}_h \text{Hep}) + \alpha_3 \alpha_6 \gamma_2 k_{15} (\alpha_5 + \gamma_5 k_{52})) k_{53},$$

$$d = -\alpha_1 \alpha_2 \alpha_5 Fe_{\text{ex}} (\gamma_3 + \hat{\gamma}_h \text{Hep}) (k_{15})^2 (\alpha_5 + \gamma_5 k_{53}).$$

# Stability of a system



- 1 Locally Stable
- 2 Globally Stable
- 3 Unstable



# The Proposal

## GOAL

Prove or disprove mathematically the global stability of  $\dot{x} = (x_1, \dots, x_5)$  for all initial conditions  $x(0) = (x_1(0), \dots, x_5(0)) \in \mathbb{R}_{>0}^5$ .

In other words, I want to prove that

$$\lim_{t \rightarrow \infty} x(t) = \bar{x}.$$

# Proving Local Stability

- The main goal of Chifman *et al.* was proving local stability
- **First approach:** Prove local stability

# Methods for Local Stability

## Jacobian Matrix and Eigenvalues

With the Jacobian matrix of the system we find the eigenvalues by using the characteristic equation:

$$\det(J - \lambda I).$$

If all the eigenvalues have negative real part, then the system is locally stable.

# Hurwitz Matrix

Given a real polynomial

$$\mathcal{P}(\lambda) = a_0\lambda^n + a_1\lambda^{n-1} + \cdots + a_{n-1}\lambda + a_n,$$

the  $n \times n$  square matrix

$$H_n = \begin{pmatrix} a_1 & a_3 & a_5 & \dots & 0 & 0 \\ a_0 & a_2 & a_4 & \dots & 0 & 0 \\ 0 & a_1 & a_3 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & a_{n-1} & 0 \\ 0 & 0 & 0 & \dots & a_{n-2} & a_n \end{pmatrix}$$

is called the *Hurwitz matrix* corresponding to the polynomial  $\mathcal{P}(\lambda)$ .

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# Methods for Local Stability

## Routh-Hurwitz criterion

For an  $n$ -degree polynomial

$$\mathcal{P}(\lambda) = a_0\lambda^n + a_1\lambda^{n-1} + \dots + a_{n-1}\lambda + a_n,$$

where  $a_i, i = 0, 1, \dots, n$  are all real, we define  $n$  Hurwitz matrices. All the roots of the polynomial have negative real part if and only if the determinants of the Hurwitz matrices are positive.

# Simplifying the System

- The system with 5 ODE's is computationally challenging because of all the unknown parameters.
- We must simplify the system in a way that is biologically possible.
- Talked with Dr.Paul Lindahl on ways to simplify the system.

# The original mathematical model

- In the original model we have proteins that help with iron import and export

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5},$$

$$\dot{x}_2 = \alpha_2 \frac{x_5}{k_{52} + x_5} - \gamma_2 x_2, \leftarrow \text{Iron import}$$

$$\dot{x}_3 = \alpha_3 \frac{k_{53}}{k_{53} + x_5} - (\gamma_3 + \gamma_h Hep) x_3, \leftarrow \text{Iron export}$$

$$\dot{x}_4 = \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5} - \gamma_4 x_4,$$

$$\dot{x}_5 = \alpha_5 \frac{k_{15}}{k_{15} + x_1} - \gamma_5 x_5.$$

# Simplifying the Model

- The model also has rates that represent the iron import and iron export

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5}$$

where  $\alpha_1$  is iron import and  $\alpha_6$  is iron export.

- We make  $x_2$  and  $x_3$  constants and combine them with their respective rates,

$$\dot{x}_1 = \alpha_1 Fe_{ex} x_2 + \gamma_4 x_4 - \alpha_6 x_1 x_3 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5}.$$

## The simplified model

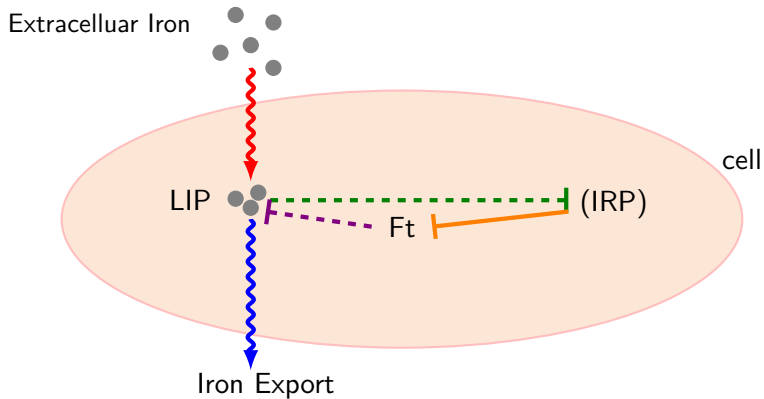
- Now, the new iron import rate is  $\hat{\alpha}_1 = \alpha_1 x_2$  and the new iron export rate is  $\hat{\alpha}_6 = \alpha_6 x_3$ . Thus the new simplified model is:

$$\dot{x}_1 = \hat{\alpha}_1 \text{Fe}_{\text{ex}} + \gamma_4 x_4 - \hat{\alpha}_6 x_1 - \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5}$$

$$\dot{x}_4 = \alpha_4 x_1 \frac{k_{54}}{k_{54} + x_5} - \gamma_4 x_4$$

$$\dot{x}_5 = \alpha_5 \frac{k_{15}}{k_{15} + x_1} - \gamma_5 x_5.$$

# The resulting control system



## Steady state of the simplified model

- For any choice of parameters, the simplified model has the following unique steady state:

$$\bar{x}_1 = \frac{\hat{\alpha}_1 \text{Fe}_{\text{ex}}}{\hat{\alpha}_6},$$

$$\bar{x}_4 = \frac{\text{Fe}_{\text{ex}}^2 \alpha_4 \gamma_5 k_{54} \hat{\alpha}_1^2 + \text{Fe}_{\text{ex}} \alpha_4 \gamma_5 k_{15} k_{54} \hat{\alpha}_1 \hat{\alpha}_6}{\text{Fe}_{\text{ex}} \gamma_4 \gamma_5 k_{54} \hat{\alpha}_1 \hat{\alpha}_6 + (\gamma_4 \gamma_5 k_{15} k_{54} + \alpha_5 \gamma_4 k_{15}) \hat{\alpha}_6^2},$$

$$\bar{x}_5 = \frac{\alpha_5 k_{15} \hat{\alpha}_6}{\text{Fe}_{\text{ex}} \gamma_5 \hat{\alpha}_1 + \gamma_5 k_{15} \hat{\alpha}_6}.$$



# Local stability of simplified system

## Theorem (Eithun and M)

*The simplified system has a unique steady state and it is locally stable.*

- 1 Verify that the coefficients of the characteristic polynomial of the Jacobian matrix are all positive.
- 2 Next, we need to verify that the principal minors  $\Delta_1, \Delta_2, \Delta_3$  of the Hurwitz matrix are positive.
- 3 By using the Routh-Hurwitz criterion the eigenvalues are all negative, thus proving that the steady state is locally stable.  $\square$

# Geometric Analysis

(Loading Video... )

- Vector fields of our system
  - ▶  $\dot{x}_1 = 0$  is the blue surface
  - ▶  $\dot{x}_4 = 0$  is the orange surface
  - ▶  $\dot{x}_5 = 0$  is the red surface.

# Geometric Analysis

## Example ( $\dot{x}_1 + \dot{x}_4$ )

First, if we look at the system we notice that

$$\dot{x}_1 + \dot{x}_4 = \hat{\alpha}_1 \text{Fe}_{\text{ex}} - \hat{\alpha}_6 x_1.$$

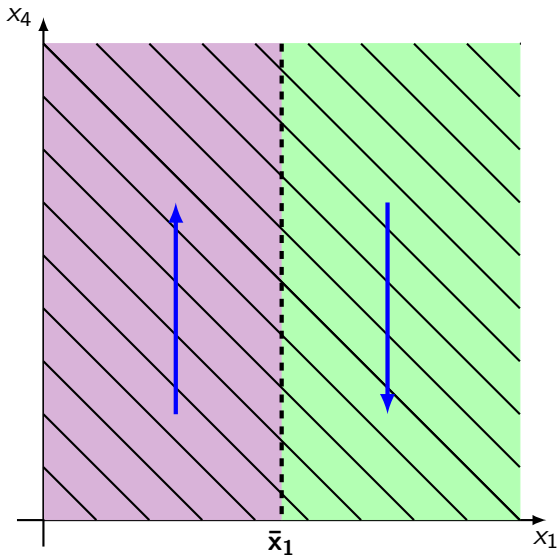
We consider the case:  $x_1 < \bar{x}_1$

Let  $\bar{x}_1 = \frac{\hat{\alpha}_1 \text{Fe}_{\text{ex}}}{\hat{\alpha}_6}$ , then

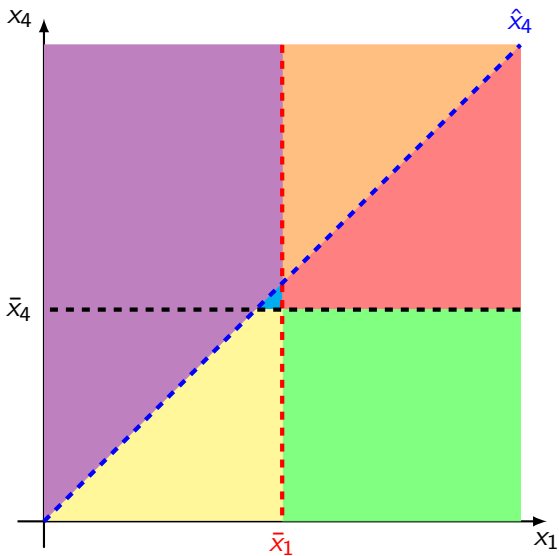
$$\dot{x}_1 + \dot{x}_4 > \hat{\alpha}_1 \text{Fe}_{\text{ex}} - \hat{\alpha}_6 x_1 > \hat{\alpha}_1 \text{Fe}_{\text{ex}} - \hat{\alpha}_6 \bar{x}_1 = 0$$

Therefore,  $\dot{x}_1 + \dot{x}_4 > 0$ . If we look at  $x_1 > \bar{x}_1$ , then  $\dot{x}_1 + \dot{x}_4 < 0$ .

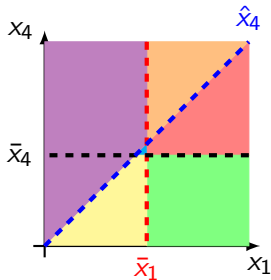
# Geometric Analysis



# The Six Regions



## Behavior of equations in the six regions



Color of region	Behavior of equations in the region
■	$\dot{x}_1 + \dot{x}_4 > 0$ & $\dot{x}_4 < 0$ & $\dot{x}_1 > 0$
■	$\dot{x}_1 + \dot{x}_4 > 0$ & If $x_5 < \bar{x}_5$ , then $\dot{x}_5 > 0$
■	$\dot{x}_5 > 0$ , $\dot{x}_4 < 0$ , and $\dot{x}_1 > 0$ . This region exists iff $x_5 < \bar{x}_5$
■	$\dot{x}_1 + \dot{x}_4 < 0$ & $\dot{x}_4 < 0$
■	$\dot{x}_1 + \dot{x}_4 < 0$ & If $x_5 > \bar{x}_5$ , then $\dot{x}_5 < 0$
■	$\dot{x}_1 + \dot{x}_4 < 0$ & If $x_5 > \bar{x}_5$ , then $\dot{x}_5 < 0$ . Otherwise, $\dot{x}_4 > 0$ and $\dot{x}_1 < 0$

# What does this tell us about the Global Stability?

- Our goal is to get to our steady state.
- By looking at the behavior of the equations in a region, we notice we are getting closer to the steady state.
- The system seems to be globally stable, but a few details remain to be worked out.

# Summary

- For a valid approximation of the Chifman *et al.* model, we showed that it has a steady state and it is locally stable.
- We also show that this model points toward global stability by using a geometric analysis.
- All of this may point to a proof for the local and global stability of the Chifman *et al.* model.



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Thank you.

# References



[1] J. Chifman, A. Kniss, P. Neupane, I. Williams, B. Leung, Z. Deng, P. Mendes, V. Hower, F.M. Torti, S.A. Akman, S.V. Torti, R. Laubenbacher, The core control system of intracellular iron homeostasis: A mathematical model, *Journal of Theoretical Biology*, Volume 300, 7 May 2012, Pages 91-99, ISSN 0022-5193, <http://dx.doi.org/10.1016/j.jtbi.2012.01.024>.